LE Series

Explosion-Proof

Liner Electric Valve Actuator

Operation Manual

Service Unique Nice Youthful Energy Honesty

SUNYEH

SUN YEH ELECTRICAL IND. CO., LTD.

SY09-C001C-EN

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1. General Information

⚠ **Failure to follow safety instructions may cause serious injury, equipment damage, or voided warranty.**

1.1 Safety Instructions

- Installation, maintenance and repair works must be performed by trained personnel.
- The handling shall follow the safety and warning instruction contained in this manual.
- The user should read and follow instructions contained in this operation manual included with the product. Failure to do this may result in damages and void warranty. Sun Yeh will not be liable for damages due to operator negligence or misuse.
- Local health and safety legislation shall be complied with.
- In a few cases, the surface temperature may exceed 60℃ (140 ℉). Please check the surface temperature before operation, using an appropriate thermometer and wearing protective gloves before operation.

1.2 Installation Notices

⚠ **All setting of opening the cover must be made in the safe place, prevent the spark from making the possibility of explosion.**

⚠ **Operating by handwheel:**
Do not use any tools to increase force on handwheel for operating as this can damage the actuator or valve.

⚠ **Instruction for handwheel:**
Remove the stopper and press the handwheel toward the actuator before handwheel operation. After manual operation, pull the handwheel out to disengage the manual override and re-place the stopper to enable the electrical control.

1.2.1 General

- DO NOT install in ambient temperatures that exceed 70 ℃ (158 ℉).
- DO NOT, under any circumstances, remove the cover of the actuator while in a hazardous location when the power is still live inside the actuator. This could cause ignition in a hazardous atmosphere.
- DO NOT, under any circumstances, use an explosion-proof electric actuator in a hazardous location that does not meet the specification which the actuator was designed for.

- Mount, test, and calibrate actuators in non-hazardous location.
- When handlng the actuator, care must be taken not to scratch, scar or deform the flame path of the cover or base of the actuator. That will negate the protection rating of the enclosure in a hazardous location.
- The explosion- proof electric actuator is shipped with mating surfces of the cover and base. When assembling them, pay attention to the mating number (QA code) to assure the protection rating in a hazardous location.
- Please read operation manual and wiring diagram carefully before installation.
- Verify that supply voltage is in accordance with the data on nameplate to prevent short circuit or electrical/electronic parts damage caused by incorrect power input.
- Turn power off before wiring or maintenance.
- There are grounding devices both inside and outside of the actuator and the ground wires should be connected properly.
- The metal plugs in conduit entries are for transit only. For long term protection fit suitable flameproof cable gland and power cable should be with a minimum withstand temperature105 ℃ (221℉). Please refer to 1.2.2 (P.3).
- Running time and rest time should be based on the standard of 1500 starts per hour or the motor may overheat and stop running.
- To avoid functional failure caused by static, do not touch any components on the PCB with metal tools or bare hands.
- Use proper techniques when installing conduit and properly seal the connection. Do not mount the actuator with conduit entries in upright position to prevent condensation from entering the unit.
- Actuator should be installed in an upright or horizontal position. Do not mount upside down or below a horizontal position.
- Periodically inspect actuator enclosure to prevent dust from accumulating.
- Perform below inspections prior to installation. Not allowed to adopt if any item is unqualified.
  - ✓ Check the marking and certificate number, to see if conforms to the indicated application.
  - ✓ All the parts of the housing are assembled in the right manner and fastened.
    ⚠ **USE FASTENERS WITH YIELD STRESS ≥ 700MPa.**
  - ✓ All the explosion-proof parts should be made without cracks or functional defects.

1.2.2 Cable Glands

⚠ **Please select the relatively explosion-proof cable connector according to the product specifications.**

- **ATEX / IECEx / TS Certification：**
  - ✓ The actuator is delivered with two conduit entries plugged by metal plugs. Use cable glands with ATEX / IECEx / TS certification and in accordance with the technical characteristics required by Ex db IIB Gb, Ex tb IIIC Db. The electrical supply cable must be suitable for power rating and with a minimum withstand temperature 105 ℃ (221 ℉).
- **CNEx Certification：**
  - ✓ The actuator is delivered with two conduit entries plugged by metal plugs. Use cable glands with CNEx certification and in accordance with the technical characteristics required by CNEx Ex db IIB Gb, Ex tD A21 IP68. The electrical supply cable must be suitable for power rating and with a minimum withstand temperature 105 ℃ (221 ℉).

1.3 Working Conditions

- **ATEX / IECEx / TS Certification：**
  - ✓ Atmospheric pressure：80 - 110 kPa.
  - ✓ Ambient temperature：- 30 ℃ to + 70 ℃ (- 22 ℉ to + 158 ℉).
  - ✓ Relative humidity：Not more than 95 % (+ 25 ℃ / 77 ℉).
  - ✓ The actuator can operate normally within tolerated variation of ± 10 % of rated supply voltage or 1 % of rated frequency.

1.4 Standards

- **ATEX European Hazardous Area**：EN60079-0, EN60079-1, EN60079-31。

Directive	Group	Ambient Temperature
ATEX II 2 GD	Ex db IIB T4 Gb	- 30 ℃ to + 70 ℃ (- 22 ℉ to + 158 ℉)
ATEX II 2 GD	Ex tb IIIC T130 ℃ Db	- 30 ℃ to + 70 ℃ (- 22 ℉ to + 158 ℉)

- **IECEx International Hazardous Area**：IEC 60079-0, IEC 60079-1, IEC60079-31。

Group	Ambient Temperature
Ex db IIB T4 Gb	- 30 ℃ to + 70 ℃ (- 22 ℉ to + 158 ℉)
Ex tb IIIC T130 ℃ Db	- 30 ℃ to + 70 ℃ (- 22 ℉ to + 158 ℉)

- **CNEx Certification**：GB3836.1, GB3836.2, GB12476.1, GB12476.5

Group	Ambient Temperature
Ex db IIB T4 Gb	- 30 ℃ to + 70 ℃ (- 22 ℉ to + 158 ℉)
Ex tD A21 IP68 T130℃	- 30 ℃ to + 70 ℃ (- 22 ℉ to + 158 ℉)

- **TS Certification**：CNS3376-0, CNS3376-1, IEC60079-31

Group	Ambient Temperature
Ex db IIB T4 Gb	- 30 ℃ to + 70 ℃ (- 22 ℉ to + 158 ℉)
Ex tb IIIC T130℃ Db	- 30 ℃ to + 70 ℃ (- 22 ℉ to + 158 ℉)

1.5 Inspection, Storage, Transport

1.5.1 Receiving / Inspection

- Carefully inspect the package for any damages resulting from shipping and report all damages to the freight carrier and seller.
- After unpacking the product and information packet, please keep the cartons and any packing materials in case of product return or replacement. Verify that the items listed in packing slip or in bill of lading are the same as what were ordered. If there is any discrepancy, please contact the seller.
- Verify that the technical data on nameplate is in accordance with what was ordered.

1.5.2 Storage

- The actuator should be stored in a dry area with relative humidity of less than 90 %（20 ± 5 ℃）and at temperature between -20 ℃ to + 40 ℃ (-4 ℉ to + 104 ℉).
- The product shall be stored with suitable protection from corrosive substance that can damage the metal and insulating parts.
- The metal plugs for temporary protection should not be removed until the actuator is ready to be cabled. Use suitable flameproof cable glands to ensure IP rated protection when installing. Please refer to 1.3 (P.3).

1.5.3 Transport

- Attach ropes or hooks for the purpose of lifting by hoist only to housing and not to handwheel.
- Actuators packaged in cartons can stand up to land, sea, or air transportation.
- Packaged actuators shall avoid of violent impact and strong vibrations and be protected from rain or snow.

1.5.4 Lubrication

- The gear train has been sufficiently lubricated at the factory. No additional lubrication is required.

2. Product Overview

LE series linear electric actuators offer thrust ranges from 250 to 2,000 kgf (550 to 4400 lbf). All models are equipped with modulating controllers and suitable for globe valves, gate valves and linear travel devices. These units are often used in the HVAC industry or industrial processes, especially suitable for steam or high temperature employment.

- **ATEX / IECEx / CNEx / TS Explosion-proof instructions：**
  - ✓ LE series explosion-proof linear electric actuators are structured as flame-proof and combustible dust-proof. The directive and standards marking are II2GD Ex db IIB T4 Gb Ta -30℃ to +70℃, Ex tb IIIC T130℃ Db. They are control devices for valves and can be used in the places, where is classified as Zone 1 or Zone 2, contained Group II A and Group II B gases, Zone 21 or Zone 22, contained the combustible dust atmospheres or the mixture circumstance with the explosive gas atmospheres and combustible dust atmospheres. Temperature group T1-T4.
  - ➢ **Certificate Number：**

    Sira14ATEX1306X

    IECEx SIR14.0108X

    CNEx14.1142X

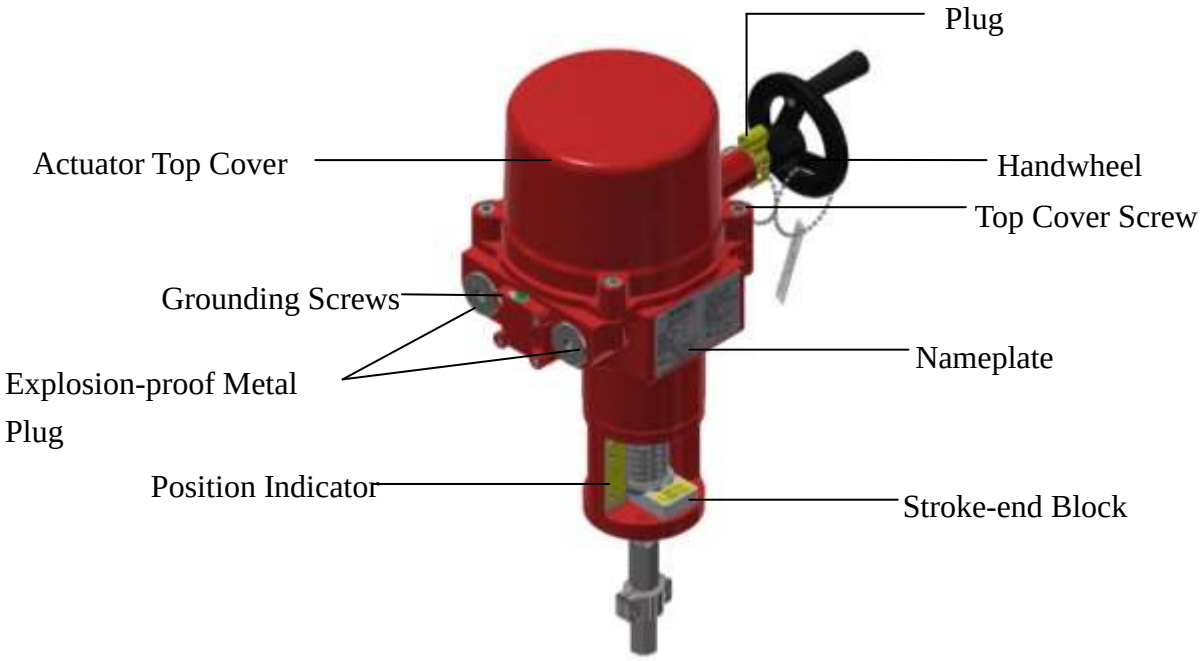
    (ITIR) 2018 No.07-0001

2.1 Features

- Enclosure conforms to IP68 (7 m / 72hrs).
- High alloy-steel gear trains with self-locking prevent back-drive.
- DC motor equipped for higher duty cycle and up to 1500 starts/hr.
- External stem position indicator.
- Low-power consumption.
- Manual operation can be applied in case of power outage.
- Built-in motor thermal protection.
- ISO 5210 mounting flange.

3. Product Mechanical Data

3.1 Parts Identification



3.2 Technical Information

Model	Thrust			Weight		Motor Power	Mounting Flange	Max. Stroke	
	kgf	lbf	N	kg	lb	Watt	ISO 5210	mm	inch
LE-250	250	550	2450	9.5	21	15	F07	50	2
LE-500	500	1100	4900	9.5	21	15	F07	50	2
LE-1000	1000	2205	9805	31	68	35	F10	100	4
LE-2000	2000	4410	19615	31	68	35	F10	100	4

3.3 Actuator Type

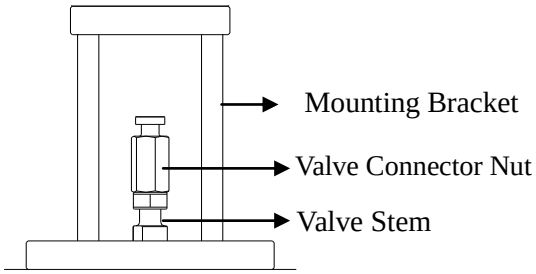
LE-❶-❷-❸

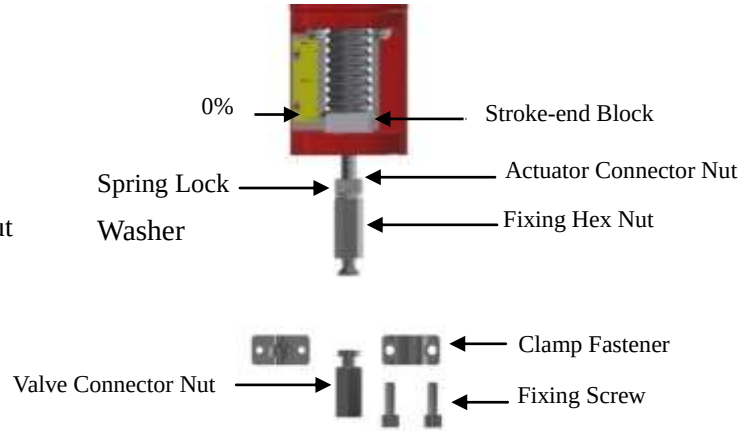
❶ Type	❷Voltage	❸Control Mode
250 500 1000 2000	24：24VAC D24：24VDC 120：110 - 120VAC 1PH 220：220 - 240VAC 1PH	F：Floating M：Modulating

3.4 Valve Mounting Instructions

⚠ **DO NOT remove the stroke end block before completing installation.**

a. The actuator shall be sized to ensure that its thrust force output and stroke length meet the load and stroke requirements of valve and its ability to overcome the required duty cycle of application. Before mounting, verify that the valve connecting nut fits with size of valve stem and the actuator is in its fully-closed position (stroke position 0%).
b. Operate the valve to the fully-closed position.
c. Remove the fixing screws from the clamp fastener and lock the valve connector nut onto the valve stem.
d. Lock the actuator connector nut, spring lock washer, and fixing hex nut to the output shaft of the actuator as shown in figure below.
e. Install the actuator onto the mounting bracket and tighten the fixing screws securely.





f. Mount the actuator with bracket onto the valve and make sure the actuator connector nut connects the valve connector nut properly as figure below, and then tighten the fixing screws of clamp fastener securely.

⚠ **The tightening torque for both of the fixing screws must be the same to ensure the force applied evenly.**

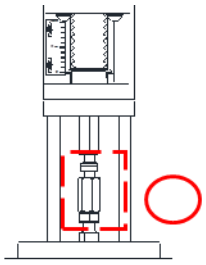


Figure 1：Correct

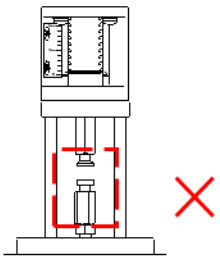


Figure 2：Wrong

Note:
Rotate the valve connector nut until it touches the surface of actuator connector nut (Figure 1).

⚠ **Valve Connector Nut must have a minimum thread engagement of 1 x the valve stem diameter. If not, adjust the Actuator Connector Nut accordingly.**

g. Tighten the valve nut with the Valve Connector Nut mutually.

⚠ **Fasten the Valve Connector Nut with wrench and tighten the valve nut toward the Valve Connector Nut (Figure 3).**

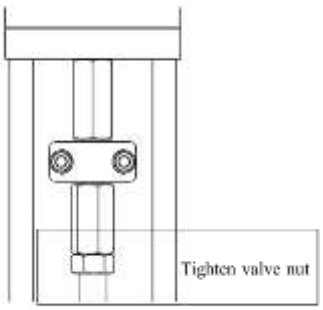


Figure 3

h. Remove the conduit entry plug to relieve the pressure inside the actuator for the ease of the top cover removal and gently remove the cover.

⚠ **The power must be off before removing the cover.**

⚠ **AFTER DE-ENERGIZING, DELAY 10 MINUTES BEFORE OPENING THE COVER.**

i. Refer to section 4.2 (P.13) for wiring notices and connect the wires according to the wiring diagram labeled inside the cover of actuator.

j. Supply power to actuator.

⚠ **Care must be taken at all times as there are live circuits present that may cause electrical shock.**

k. Assemble the cover and secure cover screws firmly after setting.

⚠

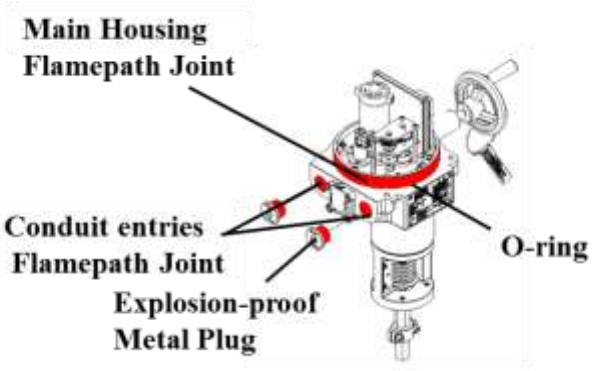
- **Please refer to Flamepath Joint and check whether there are any objects on the top cover flamepath joint and actuator.**
- **Please ensure that the O-ring seal is in good condition prior to cover installation. Slowly re-install the cover while being careful not to pinch the O-ring seal.**

⚠ **The explosion-proof enclosures are labeled with a QA code on both of the middle plate and the cover, please verify the QA code inside the cover is the same as the one on middle plate when installation. The cover is not interchangeable.**

3.5 Flamepath Joint

⚠ **During cover removal and conduit entry removal, ensure that surfaces are free from scratches or scrapes.**

⚠ **Actuator installation and maintenance must be performed by trained personnel.**



Cover Removal

Remove the conduit entry metal plugs to relieve the pressure inside the actuator for the ease of the top cover removal and gently remove the cover. DO NOT attempt to remove the top cover with a screwdriver as it will damage the surfaces.

Cover Installation

⚠ **Please ensure that the O-ring seal is in good condition prior to cover installation. Slowly re-install the cover while being careful not to pinch the O-ring seal.**

⚠ **The explosion-proof enclosures are labeled with a QA code on both of the middle plate and the cover, please verify the QA code inside the cover is the same as the one on middle plate when installation. The cover is not interchangeable.**

Please follow this table to tighten the cover screws:

Model	Screw	Allen Key	Torque
		mm	N·m
LE-250 to LE-500	M8	6	20
LE-1000 to LE-2000	M12	10	75

3.6 Nameplate Details

⚠ **Please make sure the explosion-proof specification for the product is consistent with nameplate and instruction.**

ATEX, IECEx and CNEx

TS

Nameplate indication

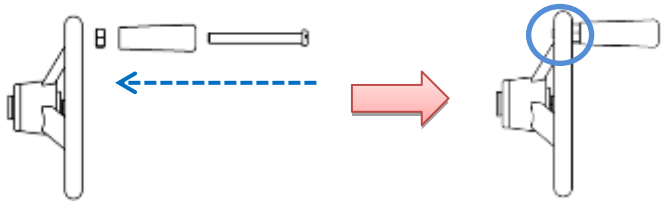
❶ Model Name	❼ Rated Current
❷ Thrust	❽ Running Speed
❸ Stroke	❾ Serial No.
❹ Enclosure Rating	❿ Date of Manufacture
❺ Motor Power	⓫ Warning
❻ Supply Voltage	⓬ Certificate

4. Mounting and Setup

4.1 Manual Device Installation

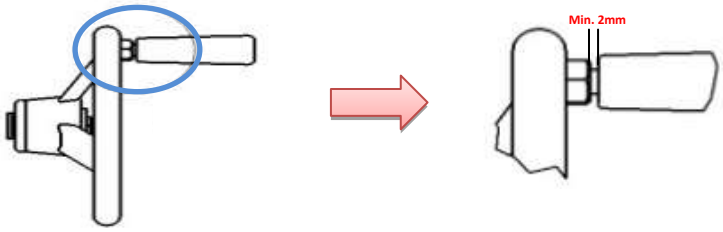
a. Pass the screw through the handle and tighten the nut onto handwheel.

⚠ **Do not overtighten.**



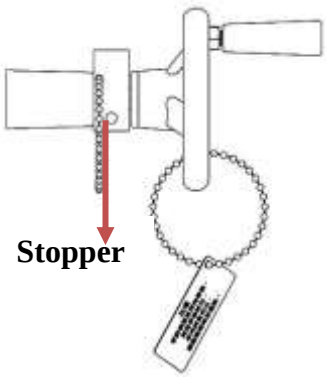
b. Secure the handle to the wheel with the slotted screw and tighten the locknut all the way down to the wheel. Ensure that the locknut is locked between the wheel and the handle.

⚠ **Leave a 2mm gap between the locknut and the handle as the figure below to allow the handle free to rotate and then to have a smooth manual operation.**



c. Assembly completed as shown in the figure below.

⚠ **Remove the stopper and press the handwheel toward the actuator before handwheel operation. After manual operation, pull the handwheel out to disengage the manual override and re-place the stopper to enable the electrical control.**



4.2 Wiring Instructions

⚠ Turn power off before making the electrical connection!

- There are grounding devices both inside and outside of the actuator (green screw) and the ground wires should be connected properly.
- The conduit entries are attached two conduit entries plugged by metal plugs, and the specification as below. Each actuator is attached with two metal plugs to conduit entries. LE-500 to LE-2600: 1/2” NPT, 3/4” NPT, M20 x 1.5 and M25 x 1.5.

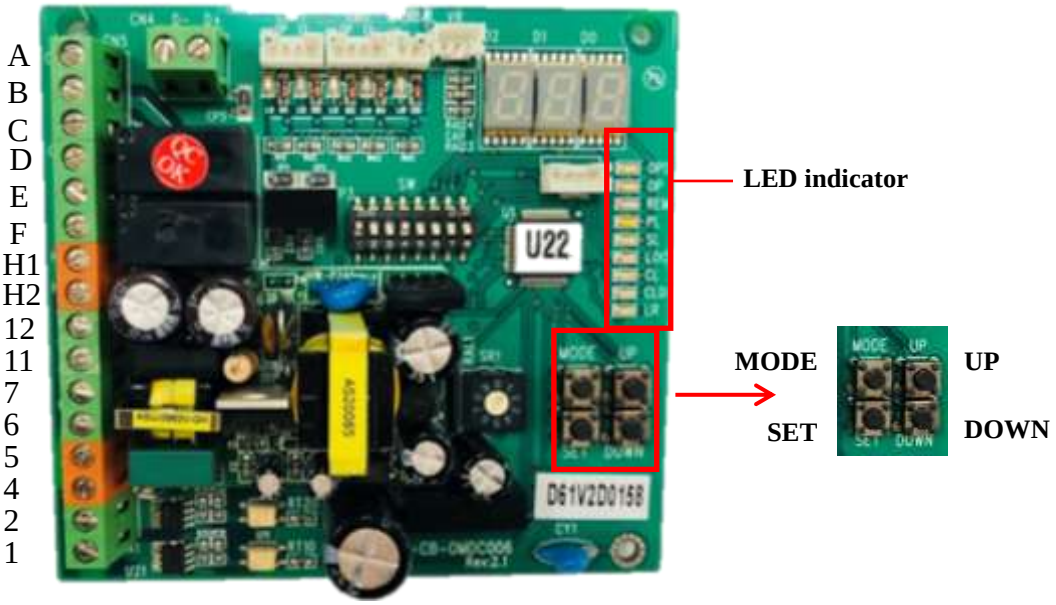
  ⚠ **Use correct size of fittings so as to not damage the threads.**
- Verify the supply power is in accordance with the data on the nameplate to prevent a short circuit and an electrical shock.

  ⚠ **Do not apply power to actuator before wiring, otherwise it can cause an electrical shock or damage components of the actuator.**
- After wiring, please tighten the conduit entries with suitable cable glands and cover properly. Unused conduit entries have to be sealed with metal plugs to reach explosion- proof function. Please refer to1.2.2 (P.3).

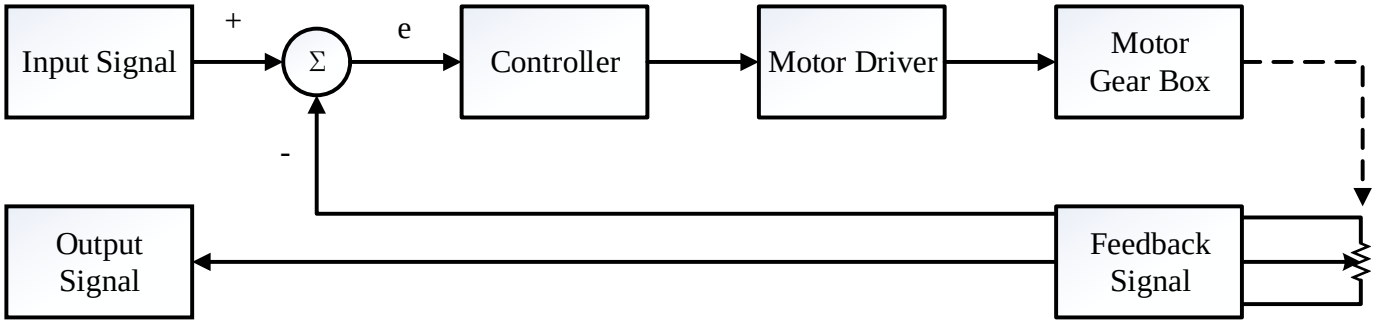
5. Modulating Control Board Adjustment

5.1 Modulating Control Board Surface

The layout is based on 110/220V voltage.



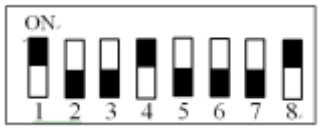
5.2 Procedure



5.3 Dip Switch Setting (SW)

The Dip Switch SW1 is a combination of 8 switches and equally divided in two rows. It is utilized to select signal type of input as well as output and fail positioning when the input signal fails. The sliders can be placed at either ON (upper) or OFF (lower) state position.

Factory settings are switches 1, 4, 8 at ON and switches 2, 3, 5, 6, 7 at OFF state.



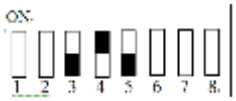
Please follow steps below if an adjustment of these settings are required.
Please restart the actuator after adjusting.

	1	2	3	4	5	6	7	8
Factory setting	ON	OFF	OFF	ON	OFF	OFF	OFF	ON
4 - 20 mA input	ON	OFF						
1 - 5 V input	OFF	OFF						
2 - 10 V input	OFF	ON						
MODBUS	ON	ON	ON	ON	ON			
4 - 20 mA output			OFF	ON	OFF			
2 - 10 V output			ON	OFF	ON			
Input 20 mA / 5 V / 10 V to operate valve to fully-open position						OFF		
Input 20 mA / 5 V / 10 V to operate valve to fully-closed position						ON		
When signal input failed, driving valve to fully-open (when S6 sets at " ON").							OFF	ON
When signal input failed, driving valve to fully-closed (when S6 sets at " ON").							ON	OFF
When signal input failed, driving valve to fully-closed (when S6 sets at " OFF").							OFF	ON
When signal input failed, driving valve to fully-open (when S6 sets at " OFF").							ON	OFF
When signal input failed, valve stays at the last position.							ON	ON

a. Input Signal Setting (1 - 2)

Input Signal	State of Switches
4 - 20 mA	1 at ON, 2 at OFF
1 - 5 V	1 at OFF, 2 at OFF
2 - 10 V	1 at OFF, 2 at ON

b. Output signal setting (3 - 5)

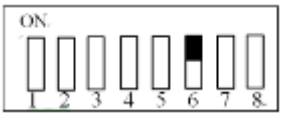


Output	State of Switches
4 - 20 mA	3 at OFF, 4 at ON, 5 at OFF
2 - 10V	3 at ON, 4 at OFF, 5 at ON

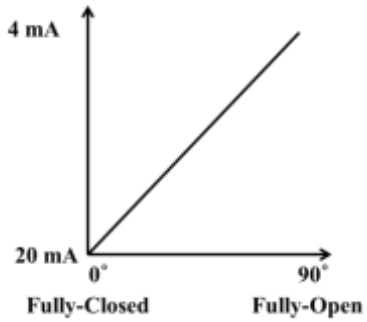
c. Setting of fail position when input signal fails (Switches 6 - 8)

⚠ **The input signal type is set by switches 1 and 2. And switch 6 is used to set the corresponding relationship between value of input signal and operation direction of actuator.**

When S6 is set to ON：



- The program defines 20 mA or 5 V or 10 V as a command for fully-closed positioning. The line graph below shows the signal level and the corresponding position of actuator.



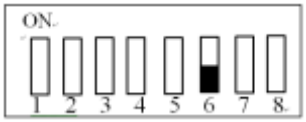
- When a low signal value is received, the actuator operates toward fully-open position and when a high signal value is received, the actuator operates toward fully-closed position.

Input Signal	Fully-Open (100%)	Fully-Closed (0%)
4 - 20 mA	4 mA	20 mA
1 - 5 V	1 V	5 V
2 - 10 V	2 V	10 V

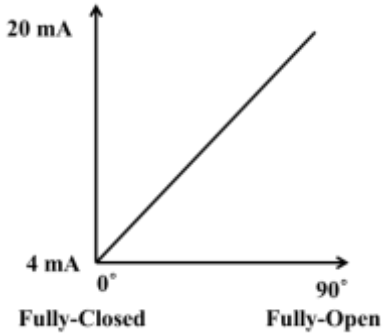
- The selection of the fail position while the input signal failed, please follow table below:

Signal Failed Position	State of Switch
Fully-Open (100%)	7 at OFF, 8 at ON
Fully-Closed (0%)	7 at ON, 8 at OFF
The Last Position	7 at ON, 8 at ON

When S6 is set to **OFF**



- The program defines 20 mA / 5 V /10 V as a command for fully-open positioning. The line graph below shows the signal level and the corresponding position of the actuator.



- When a high signal value received, the actuator operates toward fully-open position and when a low signal value received, the actuator operates toward fully-closed position.

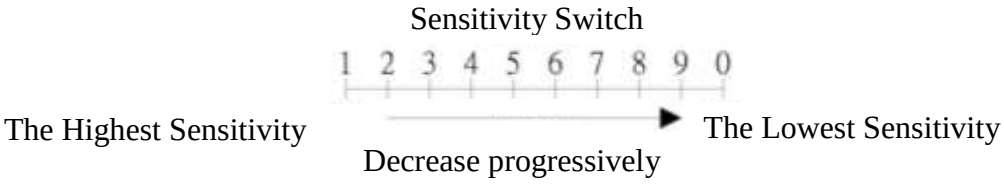
Input Signal	Fully-Open (100%)	Fully-Closed (0%)
4 - 20 mA	20 mA	4 mA
1 - 5 V	5V	1V
2 - 10 V	10V	2V

- The selection of the fail position while the input signal failed, please follow table below:

Signal Failed Position	Setting of Switch
Fully-Open (100%)	7 at ON, 8 at OFF
Fully-Closed (0%)	7 at OFF, 8 at ON.
The Last Position	7 at ON, 8 at ON.

5.4 Sensitivity Switch Setting (SR1)

When the sensitivity setting is higher, the resolution of the input signal will be higher, and relatively the dead band will be smaller. Excessive high sensitivity setting may cause the actuator to keep hunting and could not run to the desired position which will lead to the thermostat inside the motor to trip because of overheating, and finally the actuator will shut down. If this situation happens, it is suggested to turn down the sensitivity setting.

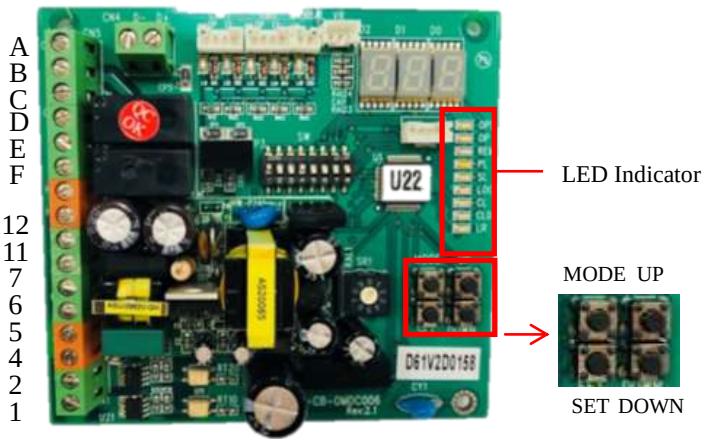


- **Original Factory setting:**
  Select "MODBUS" control, the sensitivity is preset to 1.
  Select "analog signal" control, the sensitivity is preset to 7.

Control Mode	Figure
MODBUS control	
analog signal control	

- When analog signal is selected:
  Switch to 1 : The highest sensitivity.
  Switch to 0 : The lowest sensitivity.

5.5 LED Indication



Lamp	Actuator Status
OPD	Fully-Open Position
OP	Opening Direction
REM	Remote Control Mode
PL	Alerting Signal
SL	Setting Mode
LOC	Local Control Mode
CL	Closing Direction
CLD	Fully-Closed Position
LR	MCU Indication

5.6 Stroke setting

a. Press “MODE” 5 times to get into AUo.

b. Press and hold “SET” around 5 sec until “LOC” comes on to enter Auto setting mode.

c. When the Auto setting is completed, “LOC” comes off and the actuator stops running. The travel setting is completed.

5.7 Signal Setting

⚠ **If the travel end positions have not been set up properly per 5.6, please follow steps below to recalibrate.**

- **Input signal setting for fully-closed position**

a. Press “MODE” several times until I□o displays, then press “SET” once to enter signal setting mode.

b. Press ”UP” or ”DOWN” until 2rI displays.

c. Press and hold “SET” around 3 sec until 2rI flashes.

d. Input signal according to the dip switch setting (1 V or 2 V or 4 mA).

e. Press “SET” once and then “MODE” 2 times to complete the input signal setting for fully-closed position.

- **Input signal setting for fully-open position**

a. Press ”MODE” several times until displays, then press “SET” once to enter signal setting mode.

b. Press ”UP” or ”DOWN” until displays.

c. Press and hold ”SET” around 3 sec until flashes.

d. Input signal according to the dip switch setting (5 V or 10 V or 20 mA).

e. Press ”SET” once and “MODE” 2 times to complete the input signal setting for fully-open position.

- **Output signal setting for fully-closed position**

⚠ **Use a multimeter to measure the output signal in accordance with the selected signal type.**

a. Press “MODE” several times until displays, then press “SET” once to enter signal setting mode.

b. Press ”UP” or ”DOWN” until displays.

c. Press and hold “SET” around 3 sec.

d. Select signal value by pressing “UP” or “DOWN” until the required value is achieved.

e. Press “SET” once and “MODE” 2 times to complete the output signal setting for fully-closed position.

- **Output signal setting for fully-open position**

⚠ **Use a multimeter to measure the output signal in accordance with the selected signal type.**

a. Press “MODE” several times until displays, then press “SET” once to enter signal setting mode.

b. Press ”UP” or ”DOWN” until displays.

c. Press and hold “SET” around 3 sec.

d. Select signal value by pressing “UP” or “DOWN” until the required value is achieved.

e. Press “SET” once and “Mode” twice to complete the output signal setting for fully-open position.

5.8 Warning Message

a. Press ”MODE” once until this appears , then press ”SET” once to get into warning message.

b. Press ”Up” and ”Down” to review the history log of warning message.

↑ ↑

Item Warning Message

Item (9,8,7…0)	Warning Message	Solution
(The latest data) (The oldest data)	 Abnormal signal	a. Check if the input signal fails.
	 Abnormal Handwheel	a. Check if the handwheel is pulled out completely.
	 No abnormal records	

⚠ **The latest data is listed at the top, the oldest data at the bottom.**

- **Example**

a. If you want to check the latest data, press “MODE” several times until displays → Press “Set” once → The LED display will show the latest data .

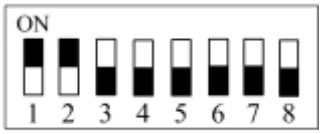
b. If you want to check the eighth data, press “MODE” several times until displays → Press “SET” once →Press “DOWN” seven times and the LED display will show the eighth data The newest data is listed at the top, the oldest data at the bottom.

5.9 MODBUS Setting

⚠ **MODBUS and modulating control cannot service at the same time.**

- **MODBUS :**

  Set switches 1 - 2 at “ON” state and switches 3 - 8 at “OFF” state.



- **Baud rate setting**

  a. Press ”MODE” twice until displays.

  b. Press ”SET” once, then will display.

  c. Press ”DOWN” 10 times until displays.

  d. Press and hold ”SET” around 3 sec until the LED indicator flashes to enter setting mode.

  e. Press ”UP” or ”DOWN” to set the required baud rate (default value #4).

Setting Value	Baud rate
4 (default)	9600
5	19200

  f. Press “SET” once to complete the setting.

- **Station setting**

  a. Press “DOWN” once, then will display.

  b. Press and hold “SET” around 3 sec until the LED indicator flashes to enter setting mode.

  c. Press ”UP” or ”DOWN” to select the required station (Station Range:1 to 127, default Station: 1).

  d. Press “Set” once to complete the setting.

- Press ”Mode” 4 times to get back to the home page.

5.10 MODBUS Parameter Address

Parameter Address (Hexadecimal)	Function	Setting range (Hexadecimal)
5	Station setting for MODBUS	1 to 127 station
6	Baud rate setting for MODBUS	4 to 5
8	Position setting (%)	0 to 64
9	Position feedback setting (%)	0 to 64

6. Troubleshooting

Floating Controller

Motor does not operate and overheats

Possible problems	Solution
a. The seating torque of valve increased caused by oxidized seals and has resulted in a torque overload on actuator.	a. Manual operate to check if it can be operated, if not, replace to a new valve.
b. Jammed pipe or valve seat stuck.	b. Check if any blockage or obstacle in pipe and remove.
c. Motor shaft or bearing were stuck.	c. Replace a new motor.
d. Handwheel is not pulled out completely	d. Press the handwheel, then pull it out completely.

The actuator operates but the motor is hot.

Possible problems	Solution
a. A torque overload caused by the valve.	a. This problem happened frequently after valve operating for a long time. It is suggested to replace with a new valve.
b. Wrong power supply.	b. Check the power supply.
c. Supply voltage was too high or too low, out the tolerance of deviation.	c. Check if the operating current values are higher than the rated values.
d. Actuator operates too frequently and exceeded duty cycle rating.	d. Adjust the system bandwidth or reduce the frequency of operation.

The valve does not operate no matter under either electrical operation or manual operation.

Possible problems	Solution
a. The actuator was mounted to the valve improperly.	a. Please refer to 3.4 (P.8 - P.9) installation steps.
b. The thrust of valve is larger than the thrust of actuator.	b. Replace a new valve or a larger size actuator.

When power is on, lamp is not functioning.

Possible problems	Solution
a. Blown fuse.	a. Replace a new fuse.
b. PCB failed.	b. Replace a new PCB.
c. Wrong supply voltage.	c. Check the power supply.

Modulating Controller

Modulating control was out of function.

Possible problems	Solution
a. Handwheel is not pulled out completely (“PL” LED indicator is glittering).	a. Press the handwheel, then pull it out completely and check if the “LI5” indicator comes on.
b. Potentiometer failed and causes actuator out of control in some section or abnormal feedback.	b. Replace a new potentiometer.
c. The sector gear of potentiometer loosened.	c. Contact technical department to solve the problem.
d. Input wrong signal type.	d. Check if the input signal is correct. Please refer to 5.3 (P.15 - P.17).
e. Modulating board failed and causes actuator can not operate or only operate in a single direction.	e. Replace a new modulating board.

The LED indicators (LR) illuminated or not illuminated (off).

Possible problems	Solution
a. Modulating board failed.	a. Replace a new modulating board.

7. Warranty

Sun Yeh Ele. Co. Ltd warrants that for a period of twelve months from the date of manufacture it will either repair or replace, at its option, any of its products which prove to be defective in material or workmanship. This warranty does not cover damage resulting from causes such as abuse, misuse, modification or tampering by users. This warranty is extended only to the immediate purchaser of the Sun Yeh product and is not transferable. To obtain service under this warranty, the purchaser must first acquire a return authorization from Sun Yeh. Products must be returned to Sun Yeh under freight prepaid.

This warranty is in lieu of all other obligations, liabilities or expressed warranties. Any implied warranties, including any implied warranty of merchantability are hereby expressly excluded. In no event shall Sun Yeh be liable for special, incidental or consequential damages arising in connection with the use of its products, or for any delay in the performance of this warranty due to cause beyond its control.

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SUNYEH

SUN YEH ELECTRICAL IND. CO., LTD.

No.68, Ln. 854, Sec. 1, Shatian Rd., Dadu Dist.,
Taichung City 432, Taiwan (R.O.C.)
TEL: +886-4-26985666
FAX: +886-4-26983668
E-mail: service@sunyeh.com
www.sunyeh.com