



OPERATION MANUAL



SUN YEH ELECTRICAL IND. CO., LTD.

SY09-C004F-EN

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1 General Information

 **Failure to follow safety instructions may cause serious injury, equipment damage, or voided warranty.**

1.1 Safety Instructions

- Installation, maintenance and repair works must be performed by trained personnel.
- The handling shall follow the safety and warning instruction contained in this manual.
- The user should read and follow instructions contained in this operation manual included with the product. Failure to do this may result in damages and void warranty. Sun Yeh will not be liable for damages due to operator negligence or misuse.
- Local health and safety legislation shall be complied with.
- In a few cases, the surface temperature may exceed 60 °C (140 °F). Please check the surface temperature before operation, using an appropriate thermometer and wearing protective gloves before operation.


1.2 Installation Notices

-  **All setting of opening the cover must be made in the safe place, prevent the spark from making the possibility of explosion.**
-  **Operating by handwheel:**
Do not use any tools to increase force on handwheel for operating as this can damage the actuator or valve.
-  **Instruction for handwheel:**
Remove the stopper and press the handwheel toward the actuator before handwheel operation. After manual operation, pull the handwheel out to disengage the manual override and re-place the stopper to enable the electrical control.


1.2.1 General

- DO NOT install in ambient temperatures that exceed 70 °C (158 °F) or 65 °C (149 °F) for Zone system.
- DO NOT, under any circumstances, remove the cover of the actuator while in a hazardous location when the power is still live inside the actuator. This could cause ignition in a hazardous atmosphere.
- DO NOT, under any circumstances, use an explosion-proof electric actuator in a hazardous location that does not meet the specification which the actuator was designed for.


- Mount, test, and calibrate actuators in non-hazardous location.
- When handling the actuator, care must be taken not to scratch, scar or deform the flame path of the cover or base of the actuator. That will negate the protection rating of the enclosure in a hazardous location.
- The explosion- proof electric actuator is shipped with mating surfaces of the cover and base. When assembling them, pay attention to the mating number (QA code) to assure the protection rating in a hazardous location.
- Please read operation manual and wiring diagram carefully before installation.
- Verify that supply voltage is in accordance with the data on nameplate to prevent short circuit or electrical/electronic parts damage caused by incorrect power input.
- Turn power off before wiring or maintenance.
- There are grounding devices both inside and outside of the actuator and the ground wires should be connected properly.
- The metal plugs in conduit entries are for transit only. For long term protection fit suitable flameproof cable gland and power cable should be with a minimum withstand temperature 105 °C (221°F). Please refer to 1.2.2 (P.3).
- Running time and rest time should be based on the standard of 75% duty cycle, or the motor may overheat and stop running.
- To avoid functional failure caused by static, do not touch any components on the PCB with metal tools or bare hands.
- Use suitable explosion-proof and water-proof cable glands to ensure it fits the conduit entry size, diameter of the cable and the enclosure protection of the actuator when wiring. The explosion-proof and water-proof cable glands must be tightened and flattened to the cable after wiring procedure. Do not remove the explosion-proof and water-proof metal plugs from unused conduit entry, be sure to fasten the top cover of the actuator to reach explosion-proof and water-proof function.
- Actuator should be installed in an upright or horizontal position. Do not mount upside down or below a horizontal position.
- Periodically inspect actuator enclosure to prevent dust from accumulating.
- Perform below inspections prior to installation. Not allowed to adopt if any item is unqualified.
 - ✓ Check the marking and certificate number, to see if conforms to the indicated application.

- ✓ All the parts of the housing are assembled in the right manner and fastened.
 -  **USE FASTENERS WITH YIELD STRESS $\geq 700\text{MPa}$.**
- ✓ All the explosion-proof parts should be made without cracks or functional defects.

1.2.2 CSA Certification Considerations

- KEEP COVER TIGHT WHILE CIRCUITS ARE ALIVE.
 -  **AFTER DE-ENERGIZING, DELAY 10 MINUTES BEFORE OPENING THE COVER.**
- SEAL REQUIRED WITHIN 2 INCHES (50 mm) OF ENCLOSURE (for Zones only).

1.2.3 Cable Glands

-  **Please select the relatively explosion-proof cable connector according to the product specifications.**
- **ATEX / UKEX / IECEx / TS Certification :**
 - ✓ The actuator is delivered with two conduit entries plugged by metal plugs. Use cable glands with ATEX / UKEX / IECEx / TS certification and in accordance with the technical characteristics required by Ex db IIB Gb, Ex tb IIIC Db. The electrical supply cable must be suitable for power rating and with a minimum withstand temperature 105 °C (221 °F).
- **CNEx / CCC Certification :**
 - ✓ The actuator is delivered with two conduit entries plugged by metal plugs. Use cable glands with CNEx certification and in accordance with the technical characteristics required by CNEx Ex db IIB T4 Gb, Ex tb IIIC T130 °C Db. The electrical supply cable must be suitable for power rating and with a minimum withstand temperature 105 °C (221 °F).
- **CSA Certification :**
 - ✓ The actuator is delivered with two conduit entries plugged by metal plugs. Use cable glands with CSA certification. The electrical supply cable must be suitable for power rating and with a minimum withstand temperature 105 °C (221 °F).

1.3 Working Conditions

- **ATEX / UKEX / IECEX / CNEEx / CCC / TS Certification:**
 - ✓ Atmospheric pressure : 80 - 110 kPa.
 - ✓ Ambient temperature : - 30 °C to + 70 °C (- 22 °F to + 158 °F).
 - ✓ Relative humidity : Not more than 95 % (+ 25 °C / 77 °F).
 - ✓ The actuator can operate normally within tolerated variation of $\pm 10\%$ of rated supply voltage or 1 % of rated frequency.
- **CSA Certification:**
 - ✓ Atmospheric pressure : 80 - 106 kPa.
 - ✓ Ambient temperature : -30 °C to +65 °C (-22 °F to +49 °F).
 - ✓ Air with normal oxygen content : 21 % (Volume).

1.4 Standards

- ATEX European Hazardous Area : EN60079-0, EN60079-1, EN60079-31 °

| Directive | Group | Ambient Temperature |
|--------------|-----------------------|--|
| ATEX II 2 GD | Ex db IIB T4 Gb | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |
| ATEX II 2 GD | Ex tb IIIC T130 °C Db | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |

- UKEX Great Britain Hazardous Area **UKCA** : EN60079-0, EN60079-1, EN60079-31

| Directive | Group | Ambient Temperature |
|--------------|-----------------------|--|
| UKCA II 2 GD | Ex db IIB T4 Gb | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |
| UKCA II 2 GD | Ex tb IIIC T130 °C Db | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |

- IECEX International Hazardous Area : IEC 60079-0, IEC 60079-1, IEC60079-31 °

| Group | Ambient Temperature |
|-----------------------|--|
| Ex db IIB T4 Gb | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |
| Ex tb IIIC T130 °C Db | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |

【LE Series】 Explosion-proof Liner Valve Actuator

- CSA North American Hazardous Area :

- ✓ **Zone System :**

CAN/CSA-C22.2 No. 0-20, CAN/CSA-C22.2 No. 60079-0, CAN/CSA-C22.2 No. 60079-1, CAN/CSA-C22.2 No. 60079-31, ANSI/UL 60079-0, ANSI/UL 60079-1, ANSI/UL 60079-31

| Code | Hazard Class | Permitted Zone | Type of Protection | Groups | Temp Classification | Ambient Temperature |
|----------|--------------|----------------|--------------------|------------------|---------------------|---|
| AEx / Ex | I | 1 | db | IIB, IIA | T4 | - 30 °C ~ + 65 °C (-22 °F ~ + 149 °F) |
| AEx / Ex | II | 21 | tb | IIIC, IIIB, IIIA | T130°C | - 30 °C ~ +65 °C (-22 °F ~ + 149 °F) |

- CNEEx / CCC Certification : GB/T 3836.1, GB/T 3836.2, GB/T 3836.31

| Group | Ambient Temperature |
|-----------------------|--|
| Ex db IIB T4 Gb | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |
| Ex tb IIIC T130 °C Db | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |

- TS Certification : IEC60079-0, IE 60079-1, IEC60079-31

| Group | Ambient Temperature |
|----------------------|--|
| Ex db IIB T4 Gb | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |
| Ex tb IIIC T130°C Db | - 30 °C to + 70 °C (- 22 °F to + 158 °F) |

1.5 Inspection, Storage, Transport

1.5.1 Receiving / Inspection

- Carefully inspect the package for any damages resulting from shipping and report all damages to the freight carrier and seller.
- After unpacking the product and information packet, please keep the cartons and any packing materials in case of product return or replacement. Verify that the items listed in packing slip or in bill of lading are the same as what were ordered. If there is any discrepancy, please contact the seller.
- Verify that the technical data on nameplate is in accordance with what was ordered.

1.5.2 Storage

- The actuator should be stored in a dry area with relative humidity of less than 90% (20 ± 5 °C) and at temperature between -20 °C to + 40 °C (-4 °F to + 104 °F).
- The product shall be stored with suitable protection from corrosive substance that can damage the metal and insulating parts.
- The metal plugs for temporary protection should not be removed until the actuator is ready to be cabled. Use suitable flameproof cable glands to ensure IP rated protection when installing. Please refer to 1.3 (P.4).

1.5.3 Transport

- Attach ropes or hooks for the purpose of lifting by hoist only to housing and not to handwheel.
- Actuators packaged in cartons can stand up to land, sea, or air transportation.
- Packaged actuators shall avoid of violent impact and strong vibrations and be protected from rain or snow.

1.5.4 Lubrication

- The gear train has been sufficiently lubricated at the factory. No additional lubrication is required.

2 Product Overview

LE series linear electric actuators offer thrust ranges from 250 to 2,000 kgf (550 to 4400 lbf). All models are equipped with modulating controllers and suitable for globe valves, gate valves and linear travel devices. These units are often used in the HVAC industry or industrial processes, especially suitable for steam or high temperature employment.

- **ATEX / UKEX / IECEx / CNEEx / CCC / TS Explosion-proof instructions :**

- ✓ LE series explosion-proof linear electric actuators are structured as flame-proof and combustible dust-proof. The directive and standards marking are II 2 GD Ex db IIB T4 Gb Ta -30°C to +70°C, Ex tb IIIC T130°C Db. They are control devices for valves and can be used in the places, where is classified as Zone 1 or Zone 2, contained Group II A and Group II B gases, Zone 21 or Zone 22, contained the combustible dust atmospheres or the mixture circumstance with the explosive gas atmospheres and combustible dust atmospheres. Temperature group T1-T4.

- **Certificate Number :**

Sira14ATEX1306X

IECEx SIR14.0108X

CNEEx19.2910X (CCC: 2020312307000190)

(ITIR) 2018 No.07-00011X

CSAE 21UKEX1205X

- **CSA explosion-proof instructions :**

- ✓ **Zone System** where is classified as North American Zone 1 or Zone 2 of hazardous location, contains Group IIA and Group IIB gases and temperature group T1 - T4 ; or in Zone 21 or Zone 22, contained one or several flammable dusts with the minimum flaming point over 130 °C ; or include both above flammable gases and dusts.

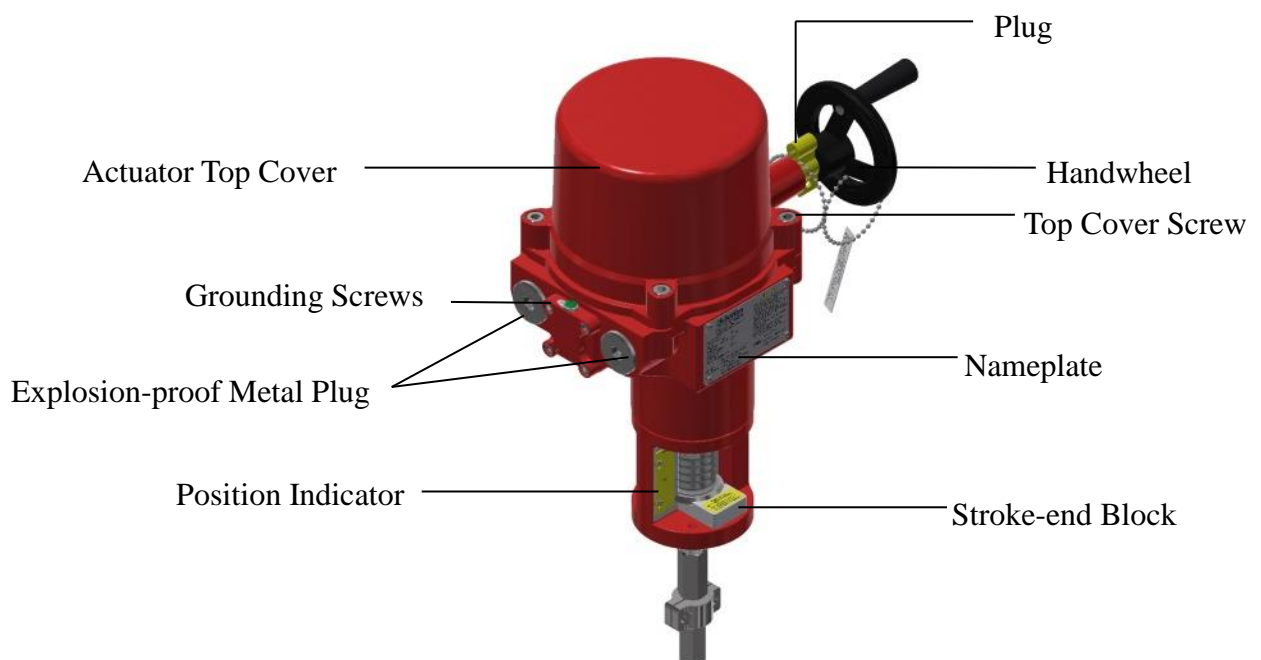
- **Certificate Number :** 80044488

2.1 Features

- Enclosure conforms to IP68 (7 m / 72 hrs).
- High alloy-steel gear trains with self-locking prevent back-drive.
- DC motor equipped with 75% duty cycle.
- External stem position indicator.
- Low-power consumption.
- Manual operation can be applied in case of power outage.
- Built-in motor thermal protection.
- ISO 5210 mounting flange.
- Thrust overload protection: The actuator will be powered off by limit switches when the output thrust exceeds the rated thrust.
- Adjustable stroke allows end user to change the stroke of the actuator per various valve stem travel.

3 Product Mechanical Data

3.1 Parts Identification



3.2 Technical Information

| Model | Thrust | | | Weight | | Motor Power | Flange Type | Max. Stroke Length | |
|---------|--------|------|--------|--------|------|-------------|-------------|--------------------|------|
| | kgf | lbf | kN | kg | lb | W | ISO 5210 | mm | inch |
| LE-250 | 250 | 550 | 2.45 | 10.5 | 23.5 | 15 | F07 | 50 | 2 |
| LE-500 | 500 | 1100 | 4.9 | 10.5 | 23.5 | 15 | F07 | 50 | 2 |
| LE-1000 | 1000 | 2205 | 9.805 | 31 | 69 | 35 | F10 | 100 | 4 |
| LE-2000 | 2000 | 4410 | 19.615 | 31 | 69 | 35 | F10 | 100 | 4 |

- Duty Cycle

| Model | Standard | Optional |
|-------------------|----------|----------|
| LE-250 to LE-2000 | 75% | N/A |

3.3 Actuator Type

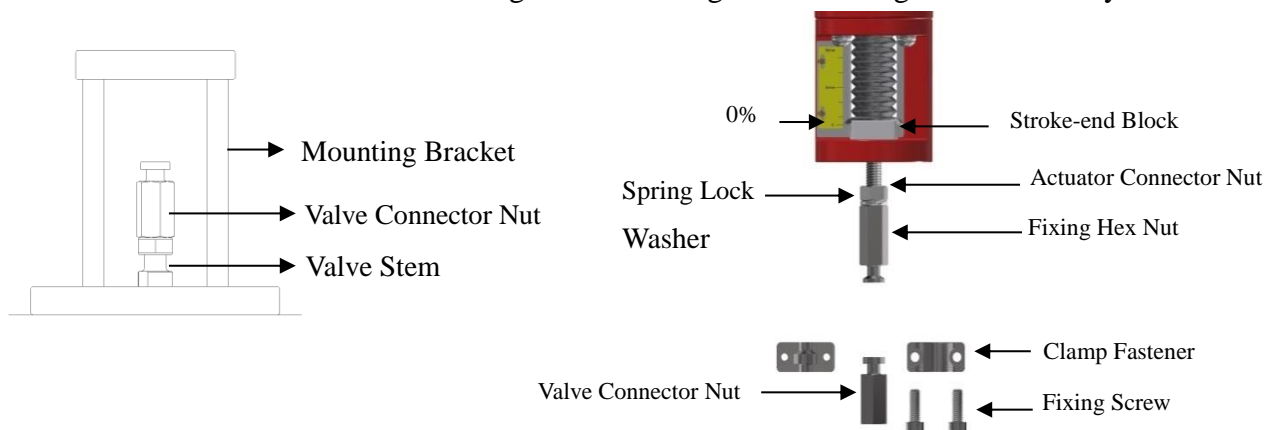
LE-①-②-③

| ① Type | ② Voltage | ③ Control Mode |
|--------|--------------------------|----------------|
| 250 | 24 : 24 V AC | F : Floating |
| 500 | D24 : 24 V DC | M : Modulating |
| 1000 | 120 : 110 - 120 V AC 1PH | |
| 2000 | 220 : 220 - 240 V AC 1PH | |

3.4 Valve Mounting Instructions

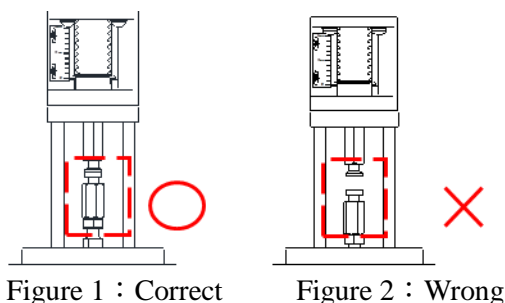
⚠ DO NOT remove the stroke end block before completing installation.

- The actuator shall be sized to ensure that its thrust force output and stroke length meet the load and stroke requirements of valve and its ability to overcome the required duty cycle of application. Before mounting, verify that the valve connecting nut fits with size of valve stem and the actuator is in its fully-closed position (stroke position 0%).
- Operate the valve to the fully-closed position.
- Remove the fixing screws from the clamp fastener and lock the valve connector nut onto the valve stem.
- Lock the actuator connector nut, spring lock washer, and fixing hex nut to the output shaft of the actuator as shown in figure below.
- Install the actuator onto the mounting bracket and tighten the fixing screws securely.



- Mount the actuator with bracket onto the valve and make sure the actuator connector nut connects the valve connector nut properly as figure below, and then tighten the fixing screws of clamp fastener securely.

⚠ The tightening torque for both of the fixing screws must be the same to ensure the force applied evenly.



Note:

Rotate the valve connector nut until it touches the surface of actuator connector nut (Figure 1).



Valve Connector Nut must have a minimum thread engagement of 1 x the valve stem diameter. If not, adjust the Actuator Connector Nut accordingly.

- g. Tighten the valve nut with the Valve Connector Nut mutually.

⚠ Fasten the Valve Connector Nut with wrench and tighten the valve nut toward the Valve Connector Nut (Figure 3).

- h. Remove the conduit entry plug to relieve the pressure inside the actuator for the ease of the top cover removal and gently remove the cover.

⚠ The power must be off before removing the cover.

⚠ AFTER DE-ENERGIZING, DELAY 10 MINUTES BEFORE OPENING THE COVER.

- i. Refer to section 4.2 (P.15) for wiring notices and connect the wires according to the wiring diagram labeled inside the cover of actuator.

- j. Supply power to actuator.

⚠ Care must be taken at all times as there are live circuits present that may cause electrical shock.

⚠ Do not remove the cover to supply power if the actuator is located in a hazardous environment. If so, please operate the unit manually.

- k. Assemble the cover and secure cover screws firmly after setting.

⚠ Please refer to Flamepath Joint and check whether there are any objects on the top cover flamepath joint and actuator.

⚠ Please ensure that the O-ring seal is in good condition prior to cover installation. Slowly re-install the cover while being careful not to pinch the O-ring seal.

⚠ The explosion-proof enclosures are labeled with a QA code on both of the middle plate and the cover, please verify the QA code inside the cover is the same as the one on middle plate when installation. The cover is not interchangeable.

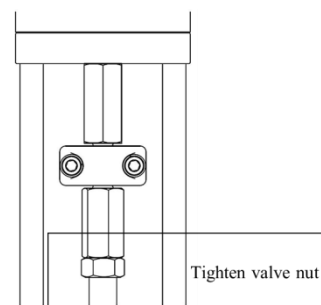


Figure 3

- After the actuator and valve are assembled completely, if the direction of the actuator (blue marked) needs to be changed according to actual working condition (Figure 4), please perform the adjustment steps as follows:

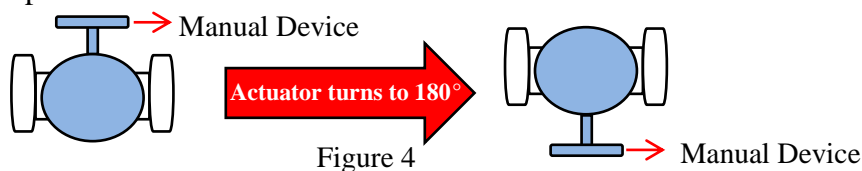


Figure 4

- a. Loosen the fixing screws and remove the clamp fastener.

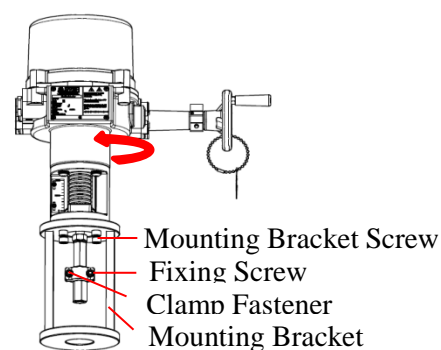
⚠ Please keep the fixing screws properly in case of missing.

- b. Loosen the mounting bracket screws.

- c. Rotate the actuator to the desired direction.

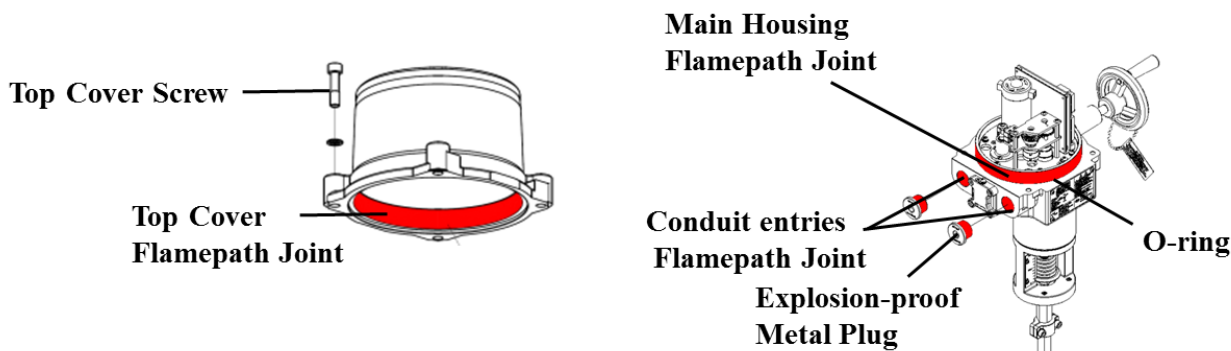
- d. Tighten the mounting bracket screws.

- e. Mount the clamp fastener and tighten the fixing screws securely.



3.5 Flamepath Joint

- ⚠ **During cover removal and conduit entry removal, ensure that surfaces are free from scratches or scrapes.**
- ⚠ **Actuator installation and maintenance must be performed by trained personnel.**



Cover Removal

Remove the conduit entry metal plugs to relieve the pressure inside the actuator for the ease of the top cover removal and gently remove the cover. DO NOT attempt to remove the top cover with a screwdriver as it will damage the surfaces.

Cover Installation

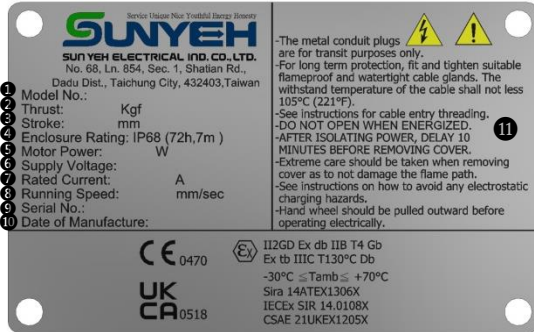
- ⚠ **Please ensure that the O-ring seal is in good condition prior to cover installation. Slowly re-install the cover while being careful not to pinch the O-ring seal.**
- ⚠ **The explosion-proof enclosures are labeled with a QA code on both of the middle plate and the cover, please verify the QA code inside the cover is the same as the one on middle plate when installation. The cover is not interchangeable.**

Please follow this table to tighten the cover screws:

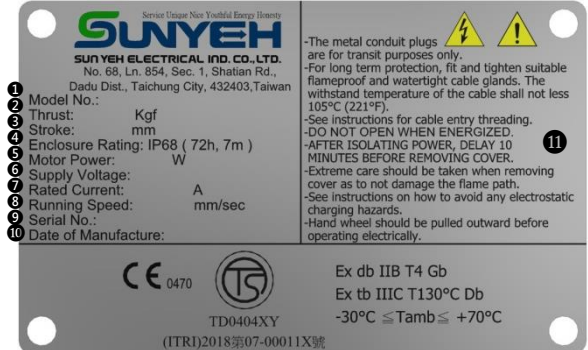
| Model | Screw | Allen Key | Torque |
|--------------------|-------|-----------|--------|
| | | mm | Nm |
| LE-250 to LE-500 | M8 | 6 | 20 |
| LE-1000 to LE-2000 | M12 | 10 | 75 |

3.6 Nameplate Details

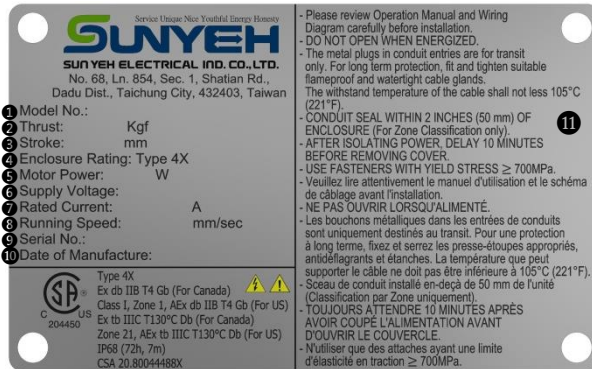
⚠ Please make sure the explosion-proof specification for the product is consistent with nameplate and instruction.



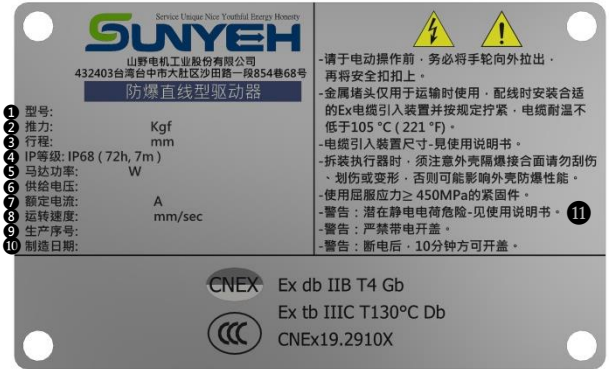
ATEX, IECEx & UKEX



TS



CSA (Zone System)



CCC & CNEEx

Nameplate indication

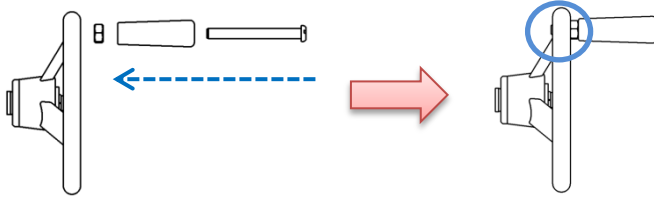
- | | |
|--------------------|-----------------------|
| ① Model Name | ⑦ Rated Current |
| ② Thrust | ⑧ Running Speed |
| ③ Stroke | ⑨ Serial No. |
| ④ Enclosure Rating | ⑩ Date of Manufacture |
| ⑤ Motor Power | ⑪ Warning |
| ⑥ Supply Voltage | ⑫ Certificate |

4 Mounting and Setup

4.1 Manual Device Installation

- a. Pass the screw through the handle and tighten the nut onto handwheel.

⚠ Do not overtighten.



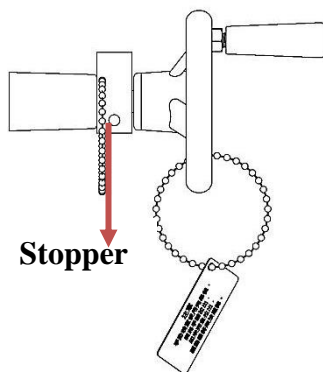
- b. Secure the handle to the wheel with the slotted screw and tighten the locknut all the way down to the wheel. Ensure that the locknut is locked between the wheel and the handle.

⚠ Leave a 2 mm gap between the locknut and the handle as the figure below to allow the handle free to rotate and then to have a smooth manual operation.





- c. Assembly completed as shown in the figure below.

⚠ Remove the stopper and press the handwheel toward the actuator before handwheel operation. After manual operation, pull the handwheel out to disengage the manual override and re-place the stopper to enable the electrical control.



4.2 Wiring Instructions

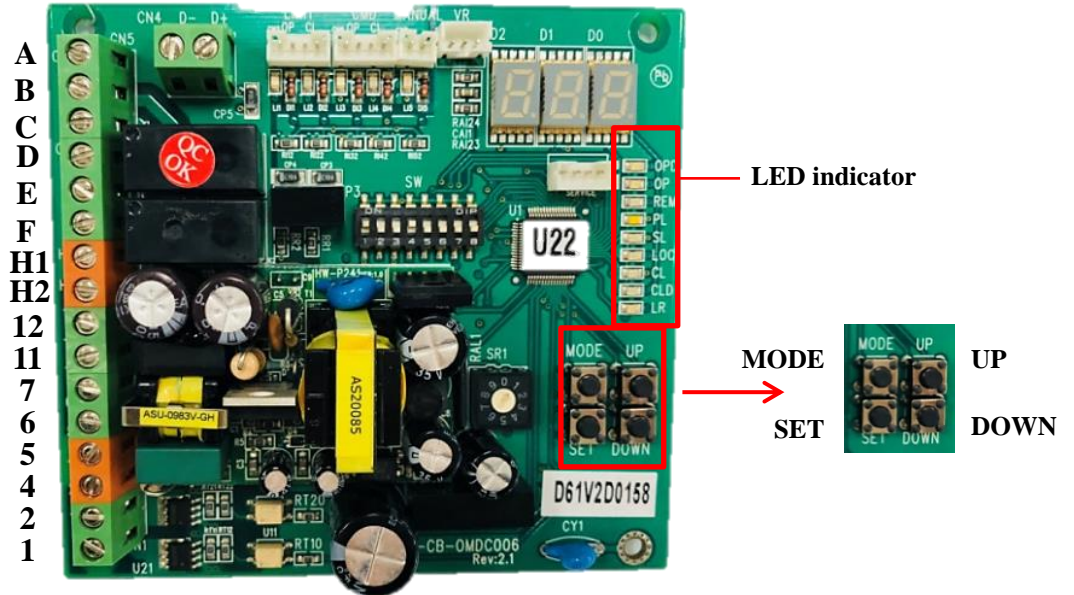
 **Turn power off before making the electrical connection!**

- There are grounding devices both inside and outside of the actuator (green screw) and the ground wires should be connected properly.
- The conduit entries are attached two conduit entries plugged by metal plugs, and the specification as below. Each actuator is attached with two metal plugs to conduit entries. LE-500 to LE-2600: 1/2" NPT, 3/4" NPT, M20 x 1.5 and M25 x 1.5.
 **Use correct size of fittings so as to not damage the threads.**
- Verify the supply power is in accordance with the data on the nameplate to prevent a short circuit and an electrical shock.
 **Do not apply power to actuator before wiring, otherwise it can cause an electrical shock or damage components of the actuator.**
- After wiring, please tighten the conduit entries with suitable cable glands and cover properly. Unused conduit entries have to be sealed with metal plugs to reach explosion-proof function. Please refer to 1.2.2 (P.3).

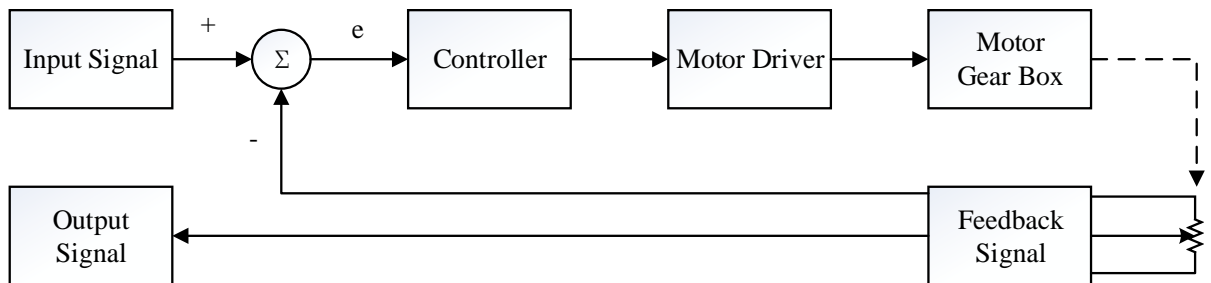
5 Modulating Control Board Adjustment

5.1 Modulating Control Board Surface

The layout is based on 110 / 220V voltage.



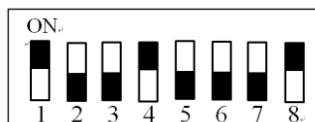
5.2 Procedure



5.3 Dip Switch Setting (SW)

The Dip Switch SW is a combination of 8 switches and equally divided in two rows. It is utilized to select signal type of input as well as output and fail positioning when the input signal fails. The sliders can be placed at either ON (upper) or OFF (lower) state position.

Factory settings are switches 1, 4, 8 at ON and switches 2, 3, 5, 6, 7 at OFF state.

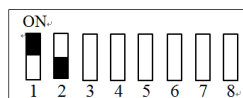


Please follow steps below if an adjustment of these settings are required.

⚠ **Please restart the actuator after adjusting.**

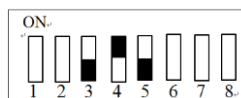
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|--|-----|-----|-----|-----|-----|-----|-----|-----|
| Factory setting | ON | OFF | OFF | ON | OFF | OFF | OFF | ON |
| 4 - 20 mA input | ON | OFF | | | | | | |
| 1 - 5 V input | OFF | OFF | | | | | | |
| 2 - 10 V input | OFF | ON | | | | | | |
| MODBUS | ON | ON | ON | ON | ON | | | |
| 4 - 20 mA output | | | OFF | ON | OFF | | | |
| 2 - 10 V output | | | ON | OFF | ON | | | |
| Input 20 mA / 5 V / 10 V to operate valve to fully-open position | | | | | | OFF | | |
| Input 20 mA / 5 V / 10 V to operate valve to fully-closed position | | | | | | ON | | |
| When signal input failed, driving valve to fully-open (when S6 sets at “ON”). | | | | | | | OFF | ON |
| When signal input failed, driving valve to fully-closed (when S6 sets at “ON”). | | | | | | | ON | OFF |
| When signal input failed, driving valve to fully-closed (when S6 sets at “OFF”). | | | | | | | OFF | ON |
| When signal input failed, driving valve to fully-open (when S6 sets at “OFF”). | | | | | | | ON | OFF |
| When signal input failed, valve stays at the last position. | | | | | | | ON | ON |

a. Input Signal Setting (1 - 2)



| Input Signal | State of Switches |
|--------------|--------------------|
| 4 - 20 mA | 1 at ON, 2 at OFF |
| 1 - 5 V | 1 at OFF, 2 at OFF |
| 2 - 10 V | 1 at OFF, 2 at ON |

b. Output signal setting (3 - 5)



| Output | State of Switches |
|-----------|-----------------------------|
| 4 - 20 mA | 3 at OFF, 4 at ON, 5 at OFF |
| 2 - 10V | 3 at ON, 4 at OFF, 5 at ON |

c. Setting of fail position when input signal fails (Switches 6 - 8)

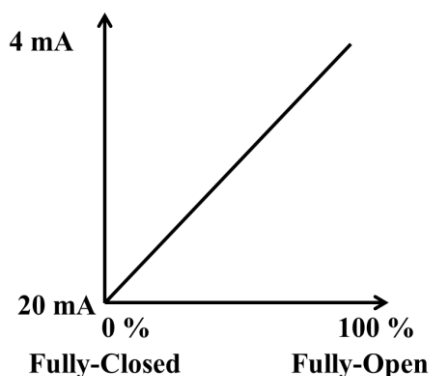


The input signal type is set by switches 1 and 2. And switch 6 is used to set the corresponding relationship between value of input signal and operation direction of actuator.

When S6 is set to ON:



- The program defines 20 mA or 5 V or 10 V as a command for fully-closed positioning. The line graph below shows the signal level and the corresponding position of actuator.



- When a low signal value is received, the actuator operates toward fully-open position and when a high signal value is received, the actuator operates toward fully-closed position.

| Input Signal | Fully-Open (100%) | Fully-Closed (0%) |
|--------------|-------------------|--------------------|
| 4 - 20 mA | 4 mA | 20 mA |
| 1 - 5 V | 1 V | 5 V |
| 2 - 10 V | 2 V | 10 V |

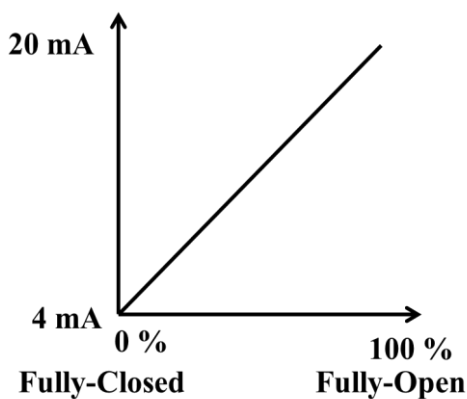
- The selection of the fail position while the input signal failed, please follow table below:

| Signal Failed Position | State of Switch |
|------------------------|-------------------|
| Fully-Open (100%) | 7 at OFF, 8 at ON |
| Fully-Closed (0%) | 7 at ON, 8 at OFF |
| The Last Position | 7 at ON, 8 at ON |

When S6 is set to **OFF**:



- The program defines 20 mA / 5 V / 10 V as a command for fully-open positioning. The line graph below shows the signal level and the corresponding position of the actuator.



- When a high signal value received, the actuator operates toward fully-open position and when a low signal value received, the actuator operates toward fully-closed position.

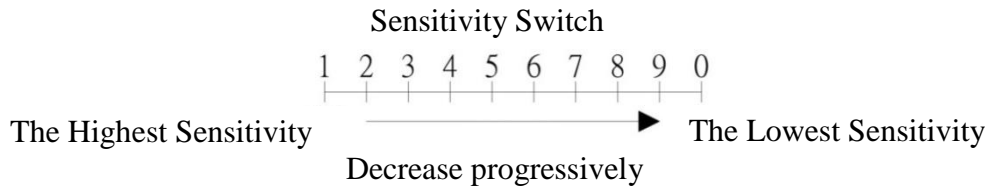
| Input Signal | Fully-Open (100%) | Fully-Closed (0%) |
|--------------|-------------------|-------------------|
| 4 - 20 mA | 20 mA | 4 mA |
| 1 - 5 V | 5V | 1V |
| 2 - 10 V | 10V | 2V |

- The selection of the fail position while the input signal failed, please follow table below:



| Signal Failed Position | Setting of Switch |
|------------------------|-------------------|
| Fully-Open (100%) | 7 at ON, 8 at OFF |
| Fully-Closed (0%) | 7 at OFF, 8 at ON |
| The Last Position | 7 at ON, 8 at ON |

5.4 Sensitivity Switch Setting (SR1)

When the sensitivity setting is higher, the resolution of the input signal will be higher, and relatively the dead band will be smaller. Excessive high sensitivity setting may cause the actuator to keep hunting and could not run to the desired position which will lead to the thermostat inside the motor to trip because of overheating, and finally the actuator will shut down. If this situation happens, it is suggested to turn down the sensitivity setting.

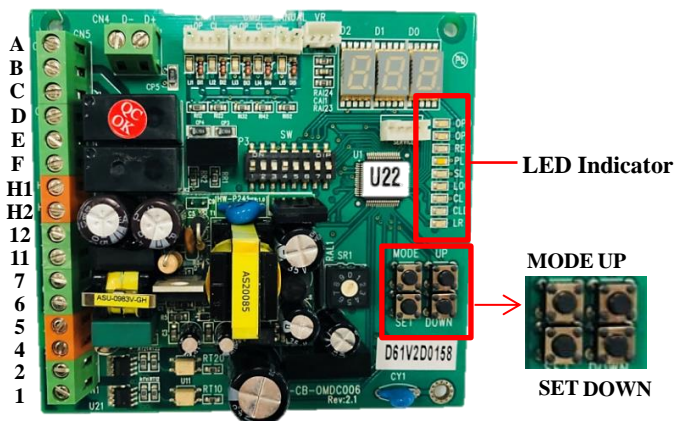


- Original Factory setting:
Select "MODBUS" control, the sensitivity is preset to 1.
Select "analog signal" control, the sensitivity is preset to 7.

| Control Mode | Figure |
|-----------------------|---|
| MODBUS control |  |
| analog signal control |  |

- When analog signal is selected:
Switch to 1: The highest sensitivity.
Switch to 0: The lowest sensitivity.

5.5 LED Indication



| Lamp | Actuator Status |
|------|-----------------------|
| OPD | Fully-Open Position |
| OP | Opening Direction |
| REM | Remote Control Mode |
| PL | Alerting Signal |
| SL | Setting Mode |
| LOC | Local Control Mode |
| CL | Closing Direction |
| CLD | Fully-Closed Position |
| LR | MCU Indication |

5.6 Stroke setting

- Press "MODE" 5 times to get into **AUo**.
- Press and hold "SET" around 5 sec until "LOC" comes on to enter Auto setting mode.
- When the Auto setting is completed, "LOC" comes off and the actuator stops running.
The travel setting is completed.

5.7 Signal Setting

 **If the travel end positions have not been set up properly per 5.6, please follow steps below to recalibrate.**

● Input signal setting for fully-closed position

- Press "MODE" several times until **1** displays, then press "SET" once to enter signal setting mode.
- Press "UP" or "DOWN" until **2r1** displays.
- Press and hold "SET" around 3 sec until **2r1** flashes.
- Input signal according to the dip switch setting (1 V or 2 V or 4 mA).
- Press "SET" once and then "MODE" 2 times to complete the input signal setting for fully-closed position.



● Input signal setting for fully-open position

- Press "MODE" several times until **1** displays, then press "SET" once to enter signal setting mode.
- Press "UP" or "DOWN" until **Fu1** displays.
- Press and hold "SET" around 3 sec until **Fu1** flashes.
- Input signal according to the dip switch setting (5 V or 10 V or 20 mA).
- Press "SET" once and "MODE" 2 times to complete the input signal setting for fully-open position.

- **Output signal setting for fully-closed position**





Use a multimeter to measure the output signal in accordance with the selected signal type.

- a. Press "MODE" several times until  displays, then press "SET" once to enter signal setting mode.
- b. Press "UP" or "DOWN" until  displays.
- c. Press and hold "SET" around 3 sec.
- d. Select signal value by pressing "UP" or "DOWN" until the required value is achieved.
- e. Press "SET" once and "MODE" 2 times to complete the output signal setting for fully-closed position.

- **Output signal setting for fully-open position**



Use a multimeter to measure the output signal in accordance with the selected signal type.

- a. Press "MODE" several times until  displays, then press "SET" once to enter signal setting mode.
- b. Press "UP" or "DOWN" until  displays.
- c. Press and hold "SET" around 3 sec.
- d. Select signal value by pressing "UP" or "DOWN" until the required value is achieved.
- e. Press "SET" once and "Mode" twice to complete the output signal setting for fully-open position.

5.8 Warning Message

- a. Press "MODE" once until this appears AL, then press "SET" once to get into warning message.
- b. Press "Up" and "Down" to review the history log of warning message.



Item Warning Message

| Item (9,8,7...0) | Warning Message | Solution |
|---|---|---|
| <div>9. (The latest data)</div> <div>8.</div> <div>7.</div> <div>6.</div> <div>5.</div> <div>4.</div> <div>3.</div> <div>2.</div> <div>1.</div> <div>0. (The oldest data)</div> | <div>01 Abnormal signal</div> <div>03 Abnormal Handwheel</div> <div>55 No abnormal records</div> | <div>a. Check if the input signal fails.</div> <div>a. Check if the handwheel is pulled out completely.</div> |

 **The latest data is listed at the top, the oldest data at the bottom.**

● Example

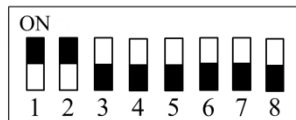
- a. If you want to check the latest data, press "MODE" several times until AL displays
→ Press "Set" once → The LED display will show the latest data 9..
- b. If you want to check the eighth data, press "MODE" several times until AL displays
→ Press "SET" once → Press "DOWN" seven times and the LED display will show the eighth data 8. The newest data is listed at the top, the oldest data at the bottom.

5.9 MODBUS Setting

⚠ MODBUS and modulating control cannot service at the same time.

- **MODBUS :**

Set switches 1 - 2 at “ON” state and switches 3 - 8 at “OFF” state.



- **Baud rate setting**

- Press ”MODE” twice until **PAR** displays.
- Press ”SET” once, then **SPd** will display.
- Press ”DOWN” 10 times until **BAU** displays.
- Press and hold ”SET” around 3 sec until the LED indicator flashes to enter setting mode.
- Press ”UP” or ”DOWN” to set the required baud rate (default value #4).

| Setting Value | Baud rate |
|---------------|-----------|
| 4 (default) | 9600 |
| 5 | 19200 |

- Press “SET” once to complete the setting.

- **Station setting**

- Press “DOWN” once, then **Id** will display.
- Press and hold “SET” around 3 sec until the LED indicator flashes to enter setting mode.
- Press ”UP” or ”DOWN” to select the required station (Station Range:1 to 127, default Station: 1).
- Press “Set” once to complete the setting.

- Press ”Mode” 4 times to get back to the home page.

5.10 MODBUS Parameter Address

| Parameter Address (Hexadecimal) | Function | Setting range (Hexadecimal) |
|-------------------------------------|-------------------------------|----------------------------------|
| 5 | Station setting for MODBUS | 1 to 127 station |
| 6 | Baud rate setting for MODBUS | 4 to 5 |
| 8 | Position setting (%) | 0 to 64 |
| 9 | Position feedback setting (%) | 0 to 64 |

6 Troubleshooting

Floating Controller

Motor does not operate and overheats

| Possible problems | Solution |
|--|--|
| a. The seating thrust of valve increased caused by oxidized seals and has resulted in a thrust overload on actuator. | a. Manual operate to check if it can be operated, if not, replace a new valve. |
| b. Jammed pipe or valve seat stuck. | b. Check if any blockage or obstacle in pipe and remove. |
| c. Motor shaft or bearing were stuck. | c. Replace a new motor. |
| d. Handwheel is not pulled out completely | d. Press the handwheel toward the actuator then pull it out completely. |

The actuator operates but the motor is hot.

| Possible problems | Solution |
|--|--|
| a. The thrust of valve overload. | a. This problem happened frequently after valve operating for a long time. It is suggested to replace a new valve. |
| b. Wrong power supply. | b. Check the power supply. |
| c. Supply voltage was too high or too low, out the tolerance of deviation. | c. Check if the operating current values are higher than the rated values. |
| d. Actuator operates too frequently and exceeded duty cycle rating. | d. Adjust the system bandwidth or reduce the frequency of operation. |

The valve does not operate no matter under either electrical operation or manual operation.

| Possible problems | Solution |
|---|--|
| a. The actuator was mounted to the valve improperly. | a. Please refer to 3.4 (P.10 - P.11) installation steps. |
| b. The thrust of valve is larger than the thrust of actuator. | b. Replace a new valve or a larger size actuator. |

When power is on, lamp is not functioning.

| Possible problems | Solution |
|--------------------------|----------------------------|
| a. Blown fuse. | a. Replace a new fuse. |
| b. PCB failed. | b. Replace a new PCB. |
| c. Wrong supply voltage. | c. Check the power supply. |

Modulating Controller

Modulating control was out of function.

| Possible problems | Solution |
|---|--|
| a. Handwheel is not pulled out completely (“PL” LED indicator is glittering). | a. Press the handwheel toward the actuator then pull it out completely and check if the “PL” indicator comes on. |
| b. Potentiometer failed and causes actuator out of control in some section or abnormal feedback. | b. Replace a new potentiometer. |
| c. Input wrong signal type. | c. Check if the input signal is correct. Please refer to 5.3 (P.17- P.18). |
| d. Modulating board failed and causes actuator can not operate or only operate in a single direction. | d. Replace a new modulating board. |

The LED indicators (LR) illuminated or not illuminated (off).

| Possible problems | Solution |
|-----------------------------|------------------------------------|
| a. Modulating board failed. | a. Replace a new modulating board. |

7 Warranty

Sun Yeh Ele. Co. Ltd warrants that for a period of twelve months from the date of manufacture it will either repair or replace, at its option, any of its products which prove to be defective in material or workmanship. This warranty does not cover damage resulting from causes such as abuse, misuse, modification or tampering by users. This warranty is extended only to the immediate purchaser of the Sun Yeh product and is not transferable. To obtain service under this warranty, the purchaser must first acquire a return authorization from Sun Yeh. Products must be returned to Sun Yeh under freight prepaid.

This warranty is in lieu of all other obligations, liabilities or expressed warranties. Any implied warranties, including any implied warranty of merchantability are hereby expressly excluded. In no event shall Sun Yeh be liable for special, incidental or consequential damages arising in connection with the use of its products, or for any delay in the performance of this warranty due to cause beyond its control.

8 Disposal

Please obey the local environment regulation for equipment scrapping.



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